

Math 2203 - Tutorial #9

1. Consider $A = \begin{bmatrix} -1 & 2 \\ 0 & -3 \end{bmatrix}$. Find A^k using the Cayley-Hamilton Theorem.

$$0 = \begin{vmatrix} -1-\lambda & 2 \\ 0 & -3-\lambda \end{vmatrix} = (-1-\lambda)(-3-\lambda) \Rightarrow \lambda = -1, \lambda = -3.$$

Characteristic Eqⁿ: $\lambda^2 + 4\lambda + 3 = 0.$

By Cayley-Hamilton Theorem, $A^2 + 4A + 3I = 0$, so it's always possible to write $A^k = c_0 I + c_1 A$ for some constants c_0 & c_1 , & $\lambda^k = c_0 + c_1 \lambda$.

$$\lambda^k = c_0 + c_1 \lambda \Rightarrow \begin{cases} (-3)^k = c_0 + c_1(-3) \\ (-1)^k = c_0 + c_1(-1) \end{cases} \Rightarrow \begin{cases} c_0 - 3c_1 = (-3)^k \\ c_0 - c_1 = (-1)^k \end{cases}$$


$$\begin{aligned} c_0 = (-1)^k + c_1 &\Rightarrow c_0 = -\frac{1}{2}(-3)^k + \frac{3}{2}(-1)^k & -2c_1 = (-3)^k - (-1)^k \\ & & c_1 = -\frac{1}{2}(-3)^k + \frac{1}{2}(-1)^k \end{aligned}$$

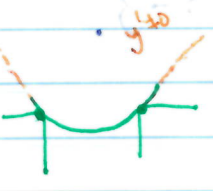
$$\text{So, } A^k = c_0 I + c_1 A = \begin{bmatrix} -\frac{1}{2}(-3)^k + \frac{3}{2}(-1)^k & 0 \\ 0 & -\frac{1}{2}(-3)^k + \frac{3}{2}(-1)^k \end{bmatrix} + c_1 \begin{bmatrix} -1 & 2 \\ 0 & -3 \end{bmatrix}$$

$$= \begin{bmatrix} (-1)^k & -(-3)^k + (-1)^k \\ 0 & (-3)^k \end{bmatrix}$$


y'' bending moment
 y''' shear force

2. Suppose a shopkeeper wants to put up a rectangular sign of length L for his store that the deflection of the sign can be modeled by the 4th-order DE $EI y^{(4)} = w(x)$. Identify the appropriate boundary conditions:

a) He uses one nail on each side. 



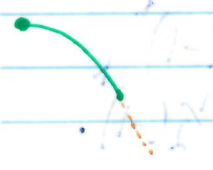
Hinged on both sides: $y(0) = 0$ $y(L) = 0$
 $y''(0) = 0$ $y''(L) = 0$


b) He uses 2 nails on each side. 



Embedded on both sides: $y(0) = 0$ $y(L) = 0$
 $y'(0) = 0$ $y'(L) = 0$

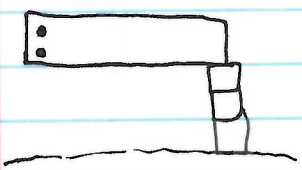
c) He uses 3 nails on the left & no nails on the right.



 Embedded on left & free on right.

$y(0) = 0$ $y''(L) = 0$
 $y'(0) = 0$ $y'''(L) = 0$

d) He uses 2 nails on left & a stack of crates on right.



Embedded on left & simply supported on right.

$y(0) = 0$ $y(L) = 0$
 $y'(0) = 0$ $y''(L) = 0$

3. Find the deflection, $y(x)$, in \square if $w(x) = w_0$ a constant & $0 < x < L$.

$$y^{(4)} = \frac{w_0}{EI}, \quad y(0) = 0, \quad y'(0) = 0, \quad y(L) = 0, \quad y''(L) = 0.$$

$m = 0$, $m = 0$ w/ multiplicity 4.

$$y_c = c_1 + c_2x + c_3x^2 + c_4x^3.$$

Undetermined
coef.:

$$y_p = Ax^4$$

$$y_p' = 4Ax^3$$

$$y_p'' = 12Ax^2$$

$$y_p''' = 24Ax$$

$$y_p^{(4)} = 24A.$$

$$y_p^{(4)} = \frac{w_0}{EI} \Leftrightarrow 24A = \frac{w_0}{EI} \Leftrightarrow A = \frac{w_0}{24EI}.$$

$$\therefore y = y_c + y_p = c_1 + c_2x + c_3x^2 + c_4x^3 + \frac{w_0}{24EI}x^4.$$

$$y(0) = 0 \Rightarrow 0 = c_1$$

$$y'(0) = 0 \Rightarrow 0 = c_2$$

$$y(L) = 0 \Rightarrow c_3L^2 + c_4L^3 + \frac{w_0}{24EI}L^4 = 0$$

$$y''(L) = 0 \Rightarrow 2c_3 + 6c_4L + \frac{w_0}{2EI}L^2 = 0$$

$$y_p = c_3x^2 + c_4x^3 + \left(\frac{w_0}{24EI}\right)x^4$$

$$y_p' = 2c_3x + 3c_4x^2 + \frac{w_0}{6EI}x^3$$

$$y_p'' = 2c_3 + 6c_4x + \frac{w_0}{2EI}x^2$$

$$c_3 = -c_4L - \frac{w_0}{24EI}L^2.$$

$$c_4 = \frac{-w_0}{12EI}L - \frac{2c_3}{3L} = \frac{-w_0}{12EI}L + \frac{c_4}{3} + \frac{w_0}{24EI} \frac{L}{3}$$

$$\Rightarrow \frac{2}{3}c_4 = \frac{-5w_0}{72EI}L \Rightarrow c_4 = \frac{-5w_0}{48EI}L \Rightarrow c_3 = \frac{5w_0}{48EI}L^2 - \frac{w_0}{24EI}L^2$$

$$\therefore y = \frac{w_0}{16EI}L^2x^2 - \frac{5}{48} \frac{w_0}{EI}Lx^3 + \frac{w_0}{24EI}x^4 = \frac{3w_0}{16EI}L^2x^2 - \frac{5w_0}{48EI}Lx^3 + \frac{w_0}{24EI}x^4$$

4. a) Solve the homog. system of linear DE's:

$$X' = \begin{bmatrix} 6 & -1 \\ 5 & 4 \end{bmatrix} X, \quad X(0) = \begin{bmatrix} -2 \\ 8 \end{bmatrix}.$$

$$0 = \begin{vmatrix} 6-\lambda & -1 \\ 5 & 4-\lambda \end{vmatrix} = 24 - 10\lambda + \lambda^2 + 5 = \lambda^2 - 10\lambda + 29.$$

$$\lambda = \frac{10 \pm \sqrt{100 - 116}}{2} = 5 \pm \frac{2i}{2}.$$

$\lambda = 5 + 2i$:

$$\begin{bmatrix} 6-5-2i & -1 & : & 0 \\ 5 & 4-5-2i & : & 0 \end{bmatrix} \xrightarrow{r_2 \leftarrow r_2 + r_1} \begin{bmatrix} 1-2i & -1 & : & 0 \\ 5 & -1-2i & : & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1-2i & -1 & : & 0 \\ 0 & 0 & : & 0 \end{bmatrix} \quad \begin{matrix} y = (1-2i)x = (1-2i)t \\ x = t \end{matrix} \quad \begin{bmatrix} 1 \\ 1-2i \end{bmatrix} = \underbrace{\begin{bmatrix} 1 \\ 1 \end{bmatrix}}_{B_1} + \underbrace{\begin{bmatrix} 0 \\ -2i \end{bmatrix}}_{B_2}.$$

So, $X_1 = e^{5t} \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \cos(2t) - \begin{bmatrix} 0 \\ -2 \end{bmatrix} \sin(2t) \right)$

and $X_2 = e^{5t} \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \sin(2t) + \begin{bmatrix} 0 \\ -2 \end{bmatrix} \cos(2t) \right).$

$$X = c_1 X_1 + c_2 X_2.$$

$$X(0) = \begin{bmatrix} -2 \\ 8 \end{bmatrix} \Rightarrow c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ -2 \end{bmatrix} = \begin{bmatrix} -2 \\ 8 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & : & -2 \\ 1 & -2 & : & 8 \end{bmatrix} \xrightarrow{r_2 \leftarrow r_2 - r_1} \begin{bmatrix} 1 & 0 & : & -2 \\ 0 & -2 & : & 10 \end{bmatrix} \quad \begin{matrix} c_1 = -2 \\ -2c_2 = 10 \Rightarrow c_2 = -5. \end{matrix}$$

$$\therefore X = -2 e^{5t} \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \cos(2t) - \begin{bmatrix} 0 \\ -2 \end{bmatrix} \sin(2t) \right) - 5 e^{5t} \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \sin(2t) + \begin{bmatrix} 0 \\ -2 \end{bmatrix} \cos(2t) \right)$$

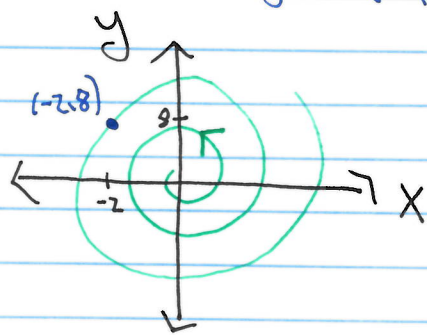
$$= \begin{bmatrix} -2 e^{5t} \cos(2t) - 5 e^{5t} \sin(2t) \\ -2 e^{5t} \cos(2t) - 2 e^{5t} \sin(2t) - 5 e^{5t} \sin(2t) + 8 e^{5t} \cos(2t) \end{bmatrix}$$

$$= \begin{bmatrix} e^{5t} (2 \cos(2t) + 5 \sin(2t)) \\ e^{5t} (8 \cos(2t) - 9 \sin(2t)) \end{bmatrix}.$$

b) Sketch the solution curve corresponding to this IVP.

Complex eigenvalues $5 \pm 2i$.

$\lambda > 0$: We'll have a spiral moving away from origin, passing through $(x(0), y(0)) = (-2, 8)$.



$$\begin{bmatrix} -2e^{i\theta} \cos(\theta) - 2e^{i\theta} \sin(\theta) \\ -2e^{i\theta} \cos(\theta) - 2e^{i\theta} \sin(\theta) \end{bmatrix} =$$

$$\begin{bmatrix} (2\cos(\theta) + 2\sin(\theta))e^{i\theta} \\ (2\cos(\theta) - 2\sin(\theta))e^{i\theta} \end{bmatrix} =$$

At $\theta = 0$, the relative error is bounded to $\frac{1}{2}$.

For $\theta = \frac{\pi}{4}$, the relative error is $\frac{1}{2}$.

At $\theta = \frac{\pi}{4}$, we have a zero. The error is $\frac{1}{2}$.

