

Math 2R 07-08 Solutions to Practice Problems # 2

1) Look them up!

2) $T: V \rightarrow V$ linear operator, u, v eigenvectors of T ; say $T(u) = \lambda_1 u$, $T(v) = \lambda_2 v$, $\lambda_1 \neq \lambda_2$.

Suppose there are $a, b \in \mathbb{R}$ s.t.

$$a u + b v = 0. \quad (1)$$

Apply T : $T(a u + b v) = T(0)$

$$a T(u) + b T(v) = 0$$

$$a \lambda_1 u + b \lambda_2 v = 0 \quad (2)$$

Solve for v in eqns (1) and (2):

$$(2) - \lambda_1(1): \quad a \lambda_1 u + b \lambda_2 v - (a \lambda_1 u + b \lambda_1 v) = 0$$

$$b(\lambda_2 - \lambda_1) v = 0$$

as ~~$b \neq 0$~~ $v \neq 0$ and $\lambda_2 \neq \lambda_1$, must have $b = 0$.

Hence $a = 0$ also.

thus u, v are independent.

$$3) \quad T: \mathbb{P}_2 \rightarrow \mathbb{P}_2$$

$$T(p(x)) = p(x) + p(-x).$$

$$\begin{aligned} \text{or } T(a+bx+cx^2) &= a+bx+cx^2 + a+b(-x)+c(-x)^2 \\ &= 2a + 2cx^2 \end{aligned}$$

$$\ker(T) = \{ p(x) : T(p(x)) = 0 \}$$

$$= \{ a+bx+cx^2 : 2a+2cx^2 = 0+0x+0x^2 \}$$

$$= \{ a+bx+cx^2 : a=0 \text{ and } c=0 \}$$

thus $\ker(T) = \text{span} \{ x \}$.

since $\dim(\ker(T)) = 1$ and $\dim(\mathbb{P}_2) = 3$, it follows by the dimension theorem that $\dim(\text{im}(T)) = 2$.

$$\text{im}(T) = \{ q(x) = q_0 + q_1x + q_2x^2 \mid \text{there exists } p(x) \text{ with } q(x) = T(p(x)) \}$$

$$= \{ q_0 + q_1x + q_2x^2 : \text{there exist } a, b, c \in \mathbb{R} \text{ with } q(x) = 2a + 2cx^2 \}$$

since we can solve $\frac{1}{2}q_0 = a$, $c = \frac{1}{2}q_2$, $b = 0$

$$\text{im}(T) = \{ q_0 + q_2x^2 \} = \text{span} \{ 1, x^2 \}.$$

/2

$$4) \quad B = \{1, x-2, x^2+3\} = \{b_1, b_2, b_3\}$$

$$P_{B \leftarrow E} = (c_B(e_1) \quad c_B(e_2) \quad c_B(e_3))$$

$$e_1 = 1 = b_1$$

$$e_2 = x = x-2+2 = 1 \cdot b_2 + 2b_1$$

$$e_3 = x^2 = x^2+3-3 = 1 \cdot b_3 - 3b_1$$

$$P_{B \leftarrow E} = \begin{pmatrix} 1 & 2 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$p(x) = a + bx + cx^2$$

$$c_E(p(x)) = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$c_B(p(x)) = P_{B \leftarrow E} c_E(p(x))$$

$$= \begin{pmatrix} 1 & 2 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$= \begin{pmatrix} a+2b-3c \\ b \\ c \end{pmatrix}$$

$$p(x) = (a+2b-3c)b_1 + b b_2 + c b_3$$

$$= (a+2b-3c)1 + b(x-2) + c(x^2+3)$$

$$5) \quad M_{EB} = (c_E T(b_1) \quad c_E T(b_2) \quad c_E T(b_3))$$

$$T(b_1) = T(1) = 2$$

$$T(b_2) = T(x-2) = x-2 + (-x)-2 = -4$$

$$T(b_3) = T(x^2+3) = x^2+3 + (-x)^2+3 = 2x^2+6$$

$$M_{EB} = \begin{pmatrix} 2 & -4 & 6 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$6) \quad A = \begin{pmatrix} 11 & -4 & -5 \\ 21 & -8 & -11 \\ 3 & -1 & 0 \end{pmatrix}$$

Solve $\det(\lambda I - A) = 0$; get $(\lambda + 1)(\lambda - 2)^2 = 0$

eigenvalues are -1 with multiplicity 1
 2 with multiplicity 2.

Solve $(-I - A)X = 0$: get $X = t \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix}$

$$E_{-1} = \text{span} \left\{ \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix} \right\}$$

Solve $(2I - A)X = 0$: get $X = t \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$.

Solve $(2I-A)^2 X = 0$: get $t \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ or $s \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$.

$$G_2 = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right\}$$

By calculation, $A \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = -1 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$, hence $AG_{-1} = G_{-1}$.

So G_{-1} is invariant.

$$A \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \in G_2 \quad A \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + 2 \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

$$A \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} -9 \\ 3 \\ -1 \end{pmatrix} = -9 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \in G_2 \quad \text{Thus } AG_2 \subseteq G_2.$$

Basis of \mathbb{R}^3 is $B = \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right\}$

Block diagonal form of A is $\begin{pmatrix} -1 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{pmatrix}$.

transition matrix is $P = P_{\substack{B \leftarrow E \\ E \leftarrow B}} = (c_E(b_1) \ c_E(b_2) \ c_E(b_3))$

$$= \begin{pmatrix} 1 & 1 & 0 \\ 3 & 1 & 1 \\ 0 & 1 & -1 \end{pmatrix}$$